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Negahdaripour, S.; Firoozfam, P.; Sabzmeydani, P.;
Computer and Robot Vision, 2005. Proceedings. The 2nd Canadian Conference
on
09-11 May 2005 Page(s):452 - 459
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1. **Image based predictive display for tele-manipulation**
Jagersand, M.;
Robotics and Automation, 1999. Proceedings. 1999 IEEE International Conference on
Volume 1, 10-15 May 1999 Page(s):550 - 556 vol.1
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2. **Predictive display models for tele-manipulation from uncalibrated camera-capture of scene geometry and appearance**
Yerex, K.; Cobzas, D.; Jagersand, M.;
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Volume 2, 14-19 Sept. 2003 Page(s):2812 - 2817 vol.2
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3. **Calibration-free robotic eye-hand coordination based on an auto disturbance-rejection controller**
Jianbo Su; Wenbin Qiu; Hongyu Ma; Peng-Yung Woo;
Robotics, IEEE Transactions on [see also Robotics and Automation, IEEE Transactions on]
Volume 20, Issue 5, Oct. 2004 Page(s):899 - 907
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4. **Estimating workpiece pose using the feature points method**
Nai-Yung Chen; Birk, J.; Kelley, R.;
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5. **Learning, tracking and recognition of 3D objects**
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6. **Computer vision assisted virtual reality calibration**
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7. **A modular system for robust positioning using feedback from stereo vision**
Hager, G.D.;
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8. **Multisensory visual servoing by a neural network**
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9. Extended-range hybrid tracker and applications to motion and camera tracking in manufacturing systems

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10. Machine vision system for the automatic identification of robot kinematic parameters

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11. A calibration free analytical solution to image points path planning that ensures visibility

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